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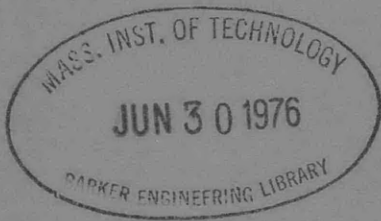
Report 4496

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THE PERFORMANCE ON THE CDC 6400 OF A RHEINBOLDT-MESZTENYI PROGRAM FOR SOLVING LARGE SPARSE SYMMETRIC SYSTEMS OF LINEAR EQUATIONS

THE PERFORMANCE ON THE CDC 6400 OF A RHEINBOLDT-MESZTENYI PROGRAM FOR SOLVING LARGE SPARSE SYMMETRIC SYSTEMS OF LINEAR EQUATIONS

Donald A. Gignac



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COMPUTATION AND MATHEMATICS DEPARTMENT
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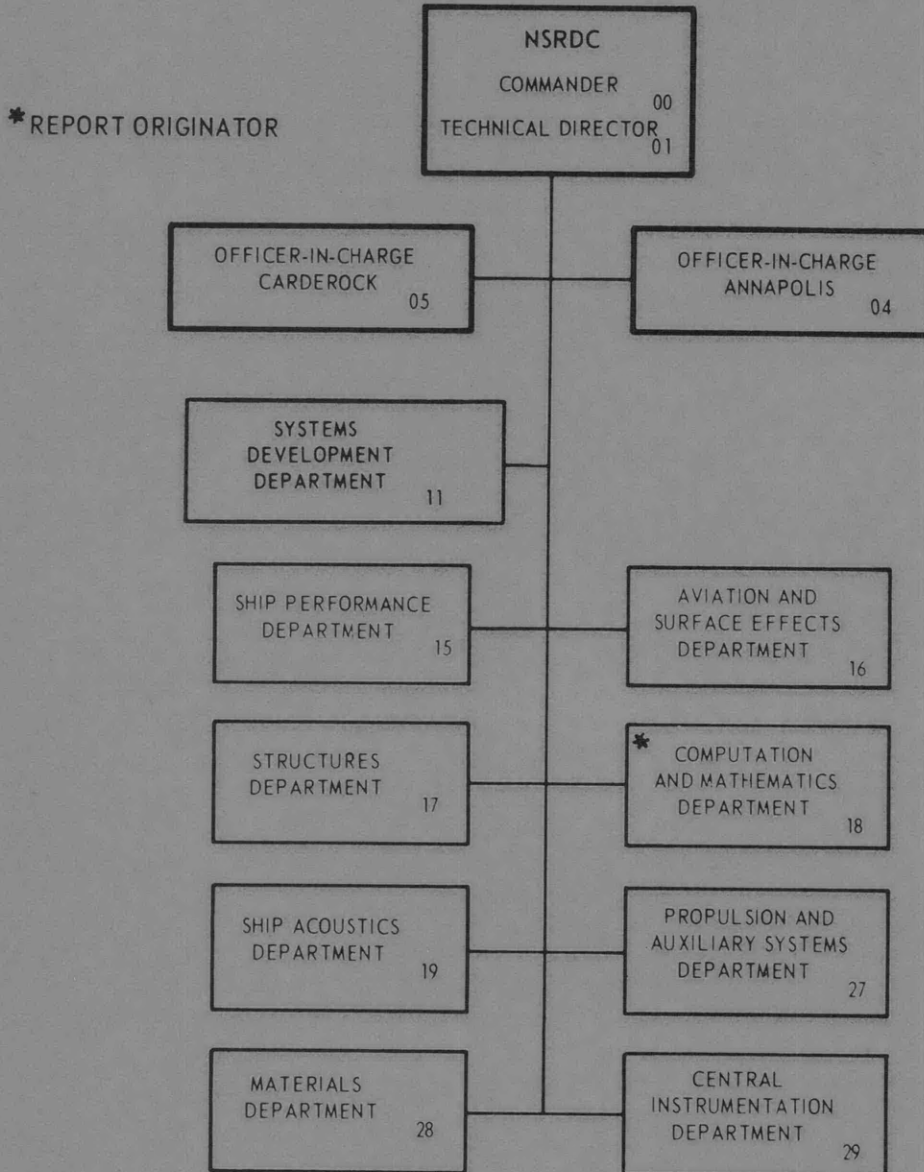
JULY 1974

Report 4496

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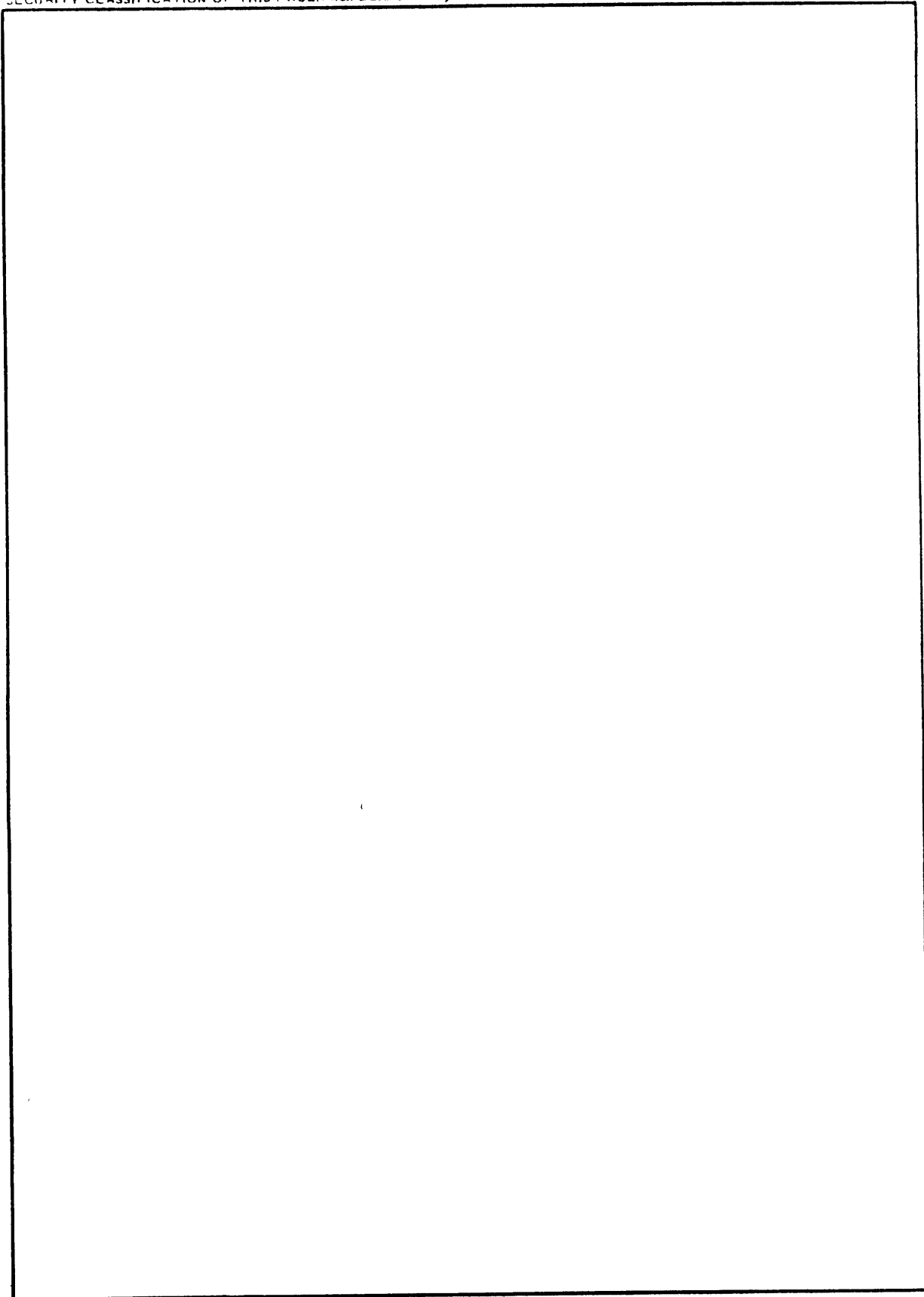
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ABSTRACT

On the CDC 6400 computer this FORTRAN Extended version of the Rheinboldt-Mesztenyi computer program for solving sparse symmetric matrix equations was tested with respect to certain sample problems representative of structural analysis problems. This program does not appear to be competitive with CSKYDG, another linear equation solver. Lack of several special features in the CDC 6400 instruction set results in high overhead for manipulating the data structures used.

ADMINISTRATIVE INFORMATION

The Naval Ship Systems Command (0311) sponsored this study under Subproject SR 014 03 01, Task 15322. The work was performed under work unit number 1-1844-004.

INTRODUCTION

In the finite element approach to static structural analysis, the computation of the solution of the equation

$$KU = P$$

a positive definite system of simultaneous linear equations, is basic. However, the order of K is often so large that it does not suffice merely to take advantage of K 's symmetry and banded structure. For such K it is necessary to consider an out-of-core solution or to devise some storage scheme which exploits sparsity more fully, or even to utilize both of these approaches together. The Rheinboldt-Mesztenyi program¹ was investigated as part of an effort to develop an improved solution capability for large sparse K . This program utilizes a data structure for storing sparse matrices based on arc-graph theory to facilitate an in-core triangular decomposition solution of $KU = P$ for such a K . The best of such programs encountered will eventually be incorporated into large-scale structural programs such as NASTRAN.

The author was recently asked for an opinion on the usefulness of the program of Professors Rheinboldt and Mesztenyi for solving the sparse matrix equations arising in structural analysis calculations on the CDC 6000 series computers. A FORTRAN version of the Rheinboldt-Mesztenyi (R-M) program for symmetric matrices was obtained and modified for the CDC 6400. This report discusses a comparison of this FORTRAN implementation of the R-M program with another FORTRAN linear equation solver, CSKYDG,² for certain sample problems.

¹ Rheinboldt, W. and Mesztenyi, C., "Problems for the Solution of Large Sparse Matrix Problems Based on the Arc-Graph Structure," University of Maryland Computer Science Center, Technical Report TR-262, September 1973.

² Gignac, D.A., "CSKYDG, An Out-of-Core Cholesky Algorithm Equation Solver for Large Positive Definite Systems of Linear Equations," Naval Ship Research and Development Center Report 4377, February 1974.

THEORY

The R-M program solves the system $KU = P$ using that form of triangular decomposition which does not require square roots. As the decomposition proceeds the rows and corresponding columns of K are interchanged in accordance with the pivoting strategy of Curtis and Reid.³ If Q represents the permutation matrix for the required row interchanges, then

$$QKQ^T = LDL^T$$

where L is a unit lower triangular matrix and D is a diagonal matrix. We then solve the triangular systems

$$\begin{aligned} LX_1 &= QP \\ DX_2 &= X_1 \\ L^T X_3 &= X_2 \end{aligned}$$

using forward or backward substitution as required, and finally obtain

$$U = Q^T X_3$$

In theory this procedure can solve $KU = P$ for any non-singular symmetric K . However, the method of Cholesky (square root method) works better for positive definite K . The Cholesky algorithm factors K into the product of a lower triangular matrix S and its transpose, that is,

$$K = SS^T,$$

then solves the triangular systems

$$\begin{aligned} SX &= P \\ S^T U &= X \end{aligned}$$

using forward or backward substitution as required.

The Cholesky algorithm has two advantages over the LDL^T procedure. First it does not require pivoting to ensure stability, making the matrix

³ Curtis, A.R., and Reid, J.K., "FORTRAN subroutines for the solution of sparse sets of linear equations," United Kingdom Atomic Energy Research Establishment, Harwell, England, Tech. Report AERE-R6844, 1971.

decomposition and the forward and backward substitutions less involved. Secondly the forward substitution can be readily incorporated into the Cholesky decomposition with a significant saving of time. (This last advantage may be realized only for a single solution of $KU = P$ for a given K .) The CSKYDG program takes advantage of these features. Wilkinson and Reinsch⁴ give details of both procedures.

EXAMPLES

Professor Mesztenyi provided the author with a FORTRAN implementation of the R-M program for the UNIVAC 1108. This program consisted of three subroutines: READ, LU, and SOLVE. The SETUP subroutine was added to facilitate the input of the matrix element. Its two arguments are NS and W. The SETUP subroutine reads from tape 4 the non-zero elements in the lines of the upper triangular half of the coefficient matrix K in the form of triplets

$$I, J, K(K,J)$$

and writes these triplets in batches of NS on tape 5. If the number of triplets is not a multiple of NS, then the last batch of triplets is filled out to NS elements by adding the appropriate number of triplets

$$1,0,0.0 \quad .$$

The righthand side of $KU = P$ is read from tape 4 and passed through the argument W. The READ subroutine then reads the triplets in batches of NS from tape 5 and sets up arcs of non-zero elements. The LU subroutine then obtains the LDL^T decomposition of K in terms of these arcs. The SOLVE subroutine then obtains U from P by solving the intermediate systems of equations. The integer packing and unpacking subroutines IPACK and IUNPK were added later.

⁴ Wilkinson, J.H. and Reinsch, C., editors, "Handbook for Automatic computation," vol. II, "Linear Algebra," Springer-Verlag, New York 1971, pp. 9-11.

After the CDC 6400 version of the R-M program had been checked out, it was compared with CSKYDG,² the author's own previously developed linear equation solver for $KU = P$. The following examples were chosen as the basis for this comparison because these are in some sense representative of systems which arise in structural analysis.

The matrix family of the first example in Table 1, A_N^1 , is generated as follows: Let N be an integer ≥ 3 . Let C_N be the tridiagonal of order N with 4's on the diagonal and a line of -1's above and below the diagonal. Let I_N be the identity matrix of order N . An $(N+1)$ -banded matrix of order N^2 , A_N^1 is constructed by

- (1) stringing N C_N submatrices along the diagonal,
- (2) inserting lines of $N-1$ $-I_N$ submatrices above and below the diagonal, and
- (3) setting the remaining elements of A_N^1 equal to 0.

The right-hand side of the system $A_N^1 X = B$ is chosen such that the exact solution X has all components equal to 1.

The matrix family of the second example in Table 2, A_N^2 , is similarly generated. This time let C_N have diagonal elements of 6. An (N^2+1) -banded matrix of order N^3 is constructed by

- (1) stringing N^2 C_N submatrices along the diagonal,
- (2) inserting lines of N^2-1 $-I_N$ submatrices above and below the diagonal,
- (3) inserting lines of N^2-N $-I_N$ submatrices as the N^{th} lines above and below the diagonal, and
- (4) setting the remaining elements of A_N^2 equal to 0.

The right-hand side of the system $A_N^2 X = B$ is chosen such that the exact solution is e_1 . These two matrix families have characteristics of matrices arising from finite difference approximations to the Dirichlet problem.

OBSERVATIONS AND CONCLUSIONS

The tables assembled in this section present the data concerning the performance of the present FORTRAN version of the R-M program on the CDC 6400. In these tables, N indicates the order of the matrix and M its bandwidth. The information in Tables 3 and 4 has been published previously.² Note that the SETUP subroutine and the NS parameter of Table 3 are different from those of Tables 1 and 2.

The CDC 6400 version of the R-M program was able to handle the order 225, bandwidth 16 case but not the order 400, bandwidth 21 case of the first matrix family using a field length of 153,400 (Table 1a). Making use of the integer packing and unpacking subroutines IPACK and IUNPK* to realize a fourfold compression of certain integer arrays, the 'packed' version of the R-M program handled the order 900, bandwidth 31 case but not the order 1225, bandwidth 36 case of the first matrix family using a field length of 145,500 (Table 1b). Similarly the 'unpacked' version of the R-M program handled the order 125, bandwidth 26 case but not the order 216, bandwidth 37 case of the second matrix family using a field length of 153,400 (Table 2a). The 'packed' version of the R-M program handled the order 343, bandwidth 50 case but not the order 512, bandwidth 65 case of the second matrix family using a field length of 145,500.

Neither the 'packed' or 'unpacked' CDC 6400 version of the R-M program seems competitive in solution times with existing FORTRAN linear equation solvers, in particular CSKYDG, for the examples investigated. Moreover, the CSKYDG program required a field length of only 70,000 to produce the results shown in Tables 3 and 4. However, the accuracy of the solutions of the two programs was comparable.

* Those subroutines were provided by Mr. Michael Golden of the Theory of Structures Branch (Code 1844). IPACK packs four integer words (each of which requires no more than fifteen bits) into one word. IUNPK reverses the packing operation. No documentation is available for these subroutines.

The R-M program was at a special disadvantage in this investigation. The "bookkeeping" procedures, so crucial to the R-M program, are most efficient when the program is coded in assembly language (COMPASS for the CDC 6400) rather than FORTRAN. Then the integer packing and unpacking procedures apparently required by the R-M program can be directly implemented in the program rather than using subroutines which are of necessity slower.

Moreover, in discussing the somewhat disappointing performance of the CDC 6400 version of the R-M program, Professor Mesztenyi pointed out that the "fetch" cycle of the CDC 6400 is more expensive than that of the UNIVAC 1108. He also noted that certain FORTRAN compilers appear to provide somewhat inefficient FORTRAN compilations, although the results published here were obtained using that compilation option of the present version of the FTN FORTRAN compiler which usually produces the most efficient code.

It is only fair to note that on the UNIVAC 1108 the performance of the assembly language version of the R-M program is quite satisfactory. For example, the LDL^T decomposition times listed in the first column of Table 5 for certain members of the first matrix family are UNIVAC 1108 assembly language times taken from Rheinboldt and Mesztenyi (page 48, Table 5). The second column of Table 5 shows the CDC 6400 FORTRAN LDL^T decomposition times from Table 1b of this report, and the third column of Table 5 gives the corresponding FORTRAN CDC 6400 CSKYDG total solution times from Table 3a of this report. Using the rule of thumb that the UNIVAC 1108 is about three times faster than the CDC 6400, these assembly language results indicate a creditable performance on the part of the R-M program. Even so, CSKYDG (for which, it must be remembered, total solution times are given) still appears to be significantly faster.

TABLE 1 - R-M SOLUTION TIMES FOR $A_L^1 X = B$

NS = 250

A - UNPACKED VERSION

N	M	SETUP (Secs.)	READ (Secs.)	SETUP+READ (Secs.)	LU (Secs.)	SOLVE (Secs.)	LU+SOLVE (Secs.)	TOTAL TIME (Secs.)
25	6	.08	.05	.12	.10	.02	.12	.24
100	11	.14	.14	.28	4.80	.29	5.09	5.37
225	16	.26	.17	.44	16.32	.97	17.29	17.73

∞

B - PACKED VERSION

N	M	SETUP (Secs.)	READ (Secs.)	SETUP+READ (Secs.)	LU (Secs.)	SOLVE (Secs.)	LU+SOLVE (Secs.)	TOTAL TIME (Secs.)
25	6	.06	.08	.14	.31	.07	.39	.53
100	11	.13	.27	.40	4.43	.64	5.07	5.47
225	16	.25	.54	.80	23.22	2.32	25.53	26.33
400	21	.47	.98	1.44	83.04	6.25	89.29	90.74
625	26	.79	1.53	2.32	198.56	12.39	210.95	213.28
900	31	1.19	2.19	3.39	479.70	25.15	504.85	508.24

TABLE 2 - R-M SOLUTION TIMES FOR $A_L^2 X = B$
 NS = 250

A - UNPACKED VERSION

N	M	SETUP (Secs.)	READ (Secs.)	SETUP+READ (Secs.)	LU (Secs.)	SOLVE (Secs.)	LU+SOLVE (Secs.)	TOTAL TIME (Secs.)
125	26	.18	.12	.30	25.23	1.05	26.28	26.58

B - PACKED VERSION

N	M	SETUP (Secs.)	READ (Secs.)	SETUP+READ (Secs.)	LU (Secs.)	SOLVE (Secs.)	LU+SOLVE (Secs.)	TOTAL TIME (Secs.)
125	26	.18	.38	.56	27.61	2.48	30.09	30.65
216	37	.36	.70	1.06	170.84	9.41	180.25	181.31
343	50	.62	1.10	1.72	511.02	20.92	531.94	533.66

TABLE 3 - CSKYDG SOLUTION TIMES FOR $A_L^1 X = B$
 NS = 10

N	M	SETUP (Secs.)	SOLUTION (Secs.)	TOTAL TIME (Secs.)
25	6	.07	.15	.21
100	11	.16	.61	.76
225	16	.48	3.07	3.55
400	21	.96	5.69	6.65
625	26	1.92	15.32	17.25
900	31	3.06	22.59	25.64
1225	36	4.87	46.49	51.36
1600	41	6.83	62.39	69.22
2025	46	9.76	108.11	117.87
2500	51	12.69	136.23	148.92
3025	56	17.25	218.10	235.35

TABLE 4 - CSKYDG SOLUTION TIMES FOR $A_L^2 X = B$

NS = 10

N	M	SETUP (Secs.)	SOLUTION (Secs.)	TOTAL TIME (Secs.)
125	26	.39	2.67	3.06
216	37	.80	7.25	8.05
343	50	1.66	17.18	18.84
512	65	3.21	44.19	47.40
729	82	5.67	96.24	101.91
1000	101	9.14	163.59	172.72
1331	122	14.69	347.39	362.08
1728	145	22.54	585.77	608.31

TABLE 5 - A FINAL COMPARISON

N	M	UNIVAC 1108 ASSEMBLY LDL ^T DECOMPOSITION TIMES (Secs.)	CDC 6400 FORTRAN LDL ^T DECOMPOSITION TIMES (Secs.)	CDC 6400 CSKYDG TOTAL SOLUTION TIMES
100	11	.343	4.43	.76
225	16	1.657	23.22	3.55
400	21	5.921	83.04	6.65

ACKNOWLEDGMENTS

The author wishes to thank the following people for their interest and assistance: Professor Charles K. Mesztenyi (University of Maryland Computer Science Center); Dr. Elizabeth H. Cuthill (NSRDC Code 1805); Mr. Michael E. Golden (NSRDC Code 1844); and Dr. Ed Cohen (Naval Ordnance Laboratory).

APPENDIX - PROGRAM LISTINGS

```

SUBROUTINE SETUP (NS, W)
C
DIMENSION X(250), II(250), JJ(250), XX(250)
DIMENSION W(1)
C
I01=4
I02=5
L=0
READ (I01) NN, MM
REWIND I02
1 WRITE (I02) NN
DO 5 I=1, NN
READ (I01) (X(K), <=1, MM)
DO 4 K=1, MM
IF (X(K)) 2, 4, 2
2 L=L+1
II(L)=I
JJ(L)=I+K-1
XX(L)=X(K)
IF (L-NS) 4, 3, 4
3 WRITE (I02) (II(KK), JJ(KK), XX(KK), KK=1, NS)
L=0
4 CONTINUE
5 CONTINUE
KLIM=L+1
DO 5 K=<KLIM, NS
II(K)=1
JJ(K)=J
6 XX(K)=0.
WRITE (I02) (II(KK), JJ(KK), XX(KK), KK=1, NS)
REWIND I02
C
READ (I01) (W(K), <=1, NN)
C
RETURN
END

```

```

SUBROUTINE READ(NS)
*****
*
*   THE READ SUBROUTINE READS THE NON-ZERO ELEMENTS OF A
*   SYMMETRIC MATRIX FROM UNIT IO, AND SETS UP THE CORRESPONDING
*   ARC-GRAPH. THE ELEMENTS ARE READ BY TRIPLET,
*   I, J, B(I, J)
*   WITH THE 1, 0, 0. TRIPLET INDICATING THE END OF INPUT RECORD.
*   ONLY THE UPPER DIAGONALS SHOULD BE GIVEN TOGETHER WITH THE
*   DIAGONAL ELEMENTS.
*
*****
C STORAGE ASSIGNMENT FOR SYMMETRIC DECOMPOSITION
C MX - THE MAXIMUM ALLOWED NUMBER OF NON-ZERO COEFFICIENTS, SB000200
C NX - THE MAXIMUM ALLOWED SIZE OF THE MATRIX. SB000300
COMMON /DIM/ MX, NX SB000400
C ARRAYS OF SIZE M - SB000500
C R - INTEGER ARRAY USED FOR ROW LINKAGE SB000700
C C - INTEGER ARRAY USED FOR COLUMN LINKAGE SB000800
C L - INTEGER ARRAY USED FOR TAGGING ( 0 OR 1 ) SB000900
C T - INTEGER ARRAY USED FOR TAGGING ( 0 OR 1 ) SB001000
C B - FL. PT. ARRAY CONTAINING THE VALUES OF THE COEFFICIENTS SB001100
C THE ARRAYS R,C,L AND T CONTAIN PACKED INTEGERS. SB001200
COMMON /ARRAYM/ R(5000),C(5000),L(5000),T(5000),B(20000)
C INTEGER R,C,T SB001500
C ARRAYS OF SIZE N - SB001600
C IP - INTEGER ARRAY CONTAINS THE SEQUENCE OF PIVOTS SB001700
C ND - INTEGER ARRAY CONTAINS THE NUMBER OF ELEMENTS SB001800
C IN A ROW OF THE UNDECOMPOSED PART OF THE MATRIX SB001900
C IH1, IH2 - ARE TEMPORARY INTEGER ARRAYS, ONE OF THEM SB002000
C MAY BE EQUIVALENCED TO IP SB002100
COMMON /ARRAYN/ IP(500),ND(500),IH1(500),IH2(500)
C INDIVIDUAL DATA - SB002300
C M - NUMBER OF NONZERO ELEMENTS SB002400
C N - SIZE OF THE MATRIX SB002500
C UP - PIVOT SELECTION PARAMETER SB002600
C CT1 - MAXIMUM ELEMENT IN THE ORIGINAL MATRIX SB002700
C CT2 - MAXIMUM ELEMENT ENCOUNTERED DURING DECOMPOSITION SB002800
COMMON /DATA/ M,N,CT1,CT2
C
C DIMENSION II(250),JJ(250),VV(250)
C
C MX=2000
C NX=1000
C IO=5
C CT1 = 0.0 SB001700
C LOOP TO ESTABLISH DIAGONALS SB001800
READ(IO) N
DO 10 I=1,N SB001900
R(I)=I
C(I)=I
L(I)=0
T(I)=0
ND(I)=0
10 B(I) = 0. SB002500

```

M = N	RS002600
C LOOP TO READ ELEMENTS	RS002700
LLIM=((N*(N+1))/2)/NS+2	
DO 25 LL=1,LLIM	
READ(IO) (II(I),JJ(I),VV(I),I=1,NS)	
C **** MODIFY THE FOLLOWING FORMAT AS NEEDED ****	RS002900
DO 20 K=1,NS	
I=II(K)	
J=JJ(K)	
V=VV(K)	
IF (ABS(V),GT,CF1) DT1=ABS(V)	RS003100
IF (I-J) 45,50,60	
C ESTABLISH ARC FOR OFF-DIAGONAL ELEMENT	RS003700
45 M = M+1	RS003800
IF (M.GT.MX) GO TO 70	RS003900
B(M) = V	RS004000
R(M)=R(I)	
C(M)=C(J)	
R(I)=M	
C(J)=M	
L(M)=0	
T(M)=0	
ND(I)=ND(I+1)	
ND(J)=ND(J+1)	
GO TO 20	RS004900
C STORE DIAGONAL	RS005000
50 B(I) = V	RS005100
ND(I)=ND(I+1)	
20 CONTINUE	
25 CONTINUE	
C END OF MATRIX ELEMENTS	
60 RETJRN	RS005400
C	RS005500
C ERROR-INSUFFICIENT STORAGE	RS005600
70 WRITE (6,80)	
80 FORMAT (2140 INSUFFICIENT STORAGE)	RS005800
STOP	RS005900
END	RS006000

SUBROUTINE LU(IPONE,UP)

```

*****
*
*   THE LU SUBROUTINE DECOMPOSES THE SYMMETRIC MATRIX.
*
*****
C
C THE ROUTINE DECOMPOSES THE SYMMETRIC                                LUS00700
C MATRIX WHICH HAD BEEN ESTABLISHED BY                                LUS00800
C THE READ ROUTINE. IF IPONE IS ZERO,                                  LUS00900
C THEN THE ROUTINE SELECTS THE PIVOTS                                 LUS01000
C ACCORDING TO THE PIVOTING STRATEGY,                                LUS01100
C OTHERWISE IT ASSUMES THAT THE ORDER                                LUS01200
C OF PIVOTS IS PROVIDED IN THE ARRAY IP.                             LUS01300
C                                                                      LUS01400
C THE ROUTINE USES TAG T FOR MARKING THE                              LUS01500
C THE ALREADY DECOMPOSED PART OF THE MATRIX.                        LUS01600
C IT USES TAG L SUCH THAT THE ROW OF A                               LUS01700
C PIVOT IS THE UNION OF THE SET OF LEFT                              LUS01800
C CONNECTED ARCS WITH TAG L = 1, AND THE                             LUS01900
C SET OF RIGHT CONNECTED ARCS WITH TAG L = 0.                        LUS02000
C
C STORAGE ASSIGNMENT FOR SYMMETRIC DECOMPOSITION                     SB000200
C MX - THE MAXIMUM ALLOWED NUMBER OF NON-ZERO COEFFICIENTS,         SB000300
C NX - THE MAXIMUM ALLOWED SIZE OF THE MATRIX.                       SB000400
C   COMMON /DIM/ MX, NX                                             SB000500
C ARRAYS OF SIZE M -                                               SB000700
C R - INTEGER ARRAY USED FOR ROW LINKAGE                             SB000800
C C - INTEGER ARRAY USED FOR COLUMN LINKAGE                         SB000900
C L - INTEGER ARRAY USED FOR TAGGING ( 0 OR 1 )                     SB001000
C T - INTEGER ARRAY USED FOR TAGGING ( 0 OR 1 )                     SB001100
C B - FL. PT. ARRAY CONTAINING THE VALUES OF THE COEFFICIENTS     SB001200
C   COMMON /ARRAY/ R(5000),C(5000),L(5000),T(5000),B(20000)
C   INTEGER R,C,T                                                    SB001500
C ARRAYS OF SIZE N -                                               SB001600
C IP - INTEGER ARRAY CONTAINS THE SEQUENCE OF PIVOTS                SB001700
C ND - INTEGER ARRAY CONTAINS THE NUMBER OF ELEMENTS                SB001800
C   IN A ROW OF THE UNDECOMPOSED PART OF THE MATRIX                SB001900
C IH1, IH2 - ARE TEMPORARY INTEGER ARRAYS, ONE OF THEM              SB002000
C   MAY BE EQUIVALENCED TO IP                                       SB002100
C   COMMON /ARRAYN/ IP(500),ND(500),IH1(500),IH2(500)
C INDIVIDUAL DATA -                                               SB002300
C M - NUMBER OF NONZERO ELEMENTS                                     SB002400
C N - SIZE OF THE MATRIX                                             SB002500
C UP - PIVOT SELECTION PARAMETER                                     SB002600
C CT1 - MAXIMUM ELEMENT IN THE ORIGINAL MATRIX                      SB002700
C CT2 - MAXIMUM ELEMENT ENCOUNTERED DURING DECOMPOSITION           SB002800
C   COMMON /DATA/ M,N,CT1,CT2
C
C LOGICAL SWP                                                       LUS02100
C
C   CT2 = CT1                                                         LUS02200
C   SWP = .TRUE.                                                       LUS02300
C   IF ( IPONE.NE.0 ) SWP=.FALSE.                                       LUS02400
C   LUS02500
C LOOP FOR THE N PIVOTS                                             LUS02600

```

DO 300 I=1,N	LUS0 2700
IF (SWP) GO TO 30	LUS0 2800
IF (I.NE.1) GO TO 2J	LUS0 2900
C SAVE THE PIVOTS IN ND IF THEY WERE GIVEN	LUS0 3000
DO 10 J=1,N	LUS0 3100
10 ND(J)=IP(J)	
C GET THE NEXT GIVEN PIVOT	LUS0 3300
20 IX=ND(I)	
IP(I)=IX	
GO TO 135	
C PIVOTS WERE NOT GIVEN, THUS FIND ONE	LUS0 3600
30 DMAX = J.	LUS0 3700
IF (UP.LE.0.) GO TO 110	LUS0 3800
C FIND MAXIMAL ELEMENT IN THE AVAILABLE DIAGONALS	LUS0 3900
DO 100 J=1,N	LUS0 4000
IF (T(J).EQ.1) GO TO 100	LUS0 4100
DMAX=AMAX1(DMAX, ABS(B(J)))	LUS0 4300
100 CONTINUE	LUS0 4400
DMAX = JP*DMAX	LUS0 4500
C NOW FIND AN AVAILABLE DIAGONAL WHOSE VALUE IS	LUS0 4600
C GREATER THAN DMAX AND HAS MINIMUM NUMBER OF	LUS0 4700
C ELEMENTS IN ITS ROW	LUS0 4800
110 IX = C	LUS0 4900
XM = J.	LUS0 5000
DO 130 J=1,N	LUS0 5100
IF (T(J).EQ.1 .OR. B(J).EQ.0.)	
1 GO TO 130	LUS0 5300
IF (ABS(B(J)).LT.DMAX)	LUS0 5400
1 GO TO 130	LUS0 5500
IF (IX.EQ.J) GO TO 12J	LUS0 5600
IF (ND(J)-NY) 120,119,130	
119 IF(ABS(B(J)).LE.XM) GO TO 130	LUS0 5900
120 IX = J	LUS0 6000
XM = ABS(B(J))	LUS0 6100
NY=ND(J)	
130 CONTINUE	LUS0 6300
IF ((IX.EQ.0).OR.	LUS0 6400
1 (XM.LT.1.E-20)) GO TO 900	LUS0 6500
IP(I)=IX	
C NOW THE PIVOT IS IN IX, SET ITS TAG T	LUS0 6700
135 K = I	LUS0 6800
T(IX)=1	
XMAX = B(IX)	LUS0 7000
C LOOP TO COLLECT THE ELEMENTS IN THE ROW OF THE PIVOT	LUS0 7100
IY = IX	LUS0 7200
C COLLECT THE LEFT CONNECTED ARCS	LUS0 7300
C WITH THEIR RIGHT INDEX VALUE	LUS0 7400
140 IY=R(IY)	
IF (IY.EQ.IX) GO TO 170	LUS0 7600
IF (L(IY).EQ.1) GO TO 140	
T(IY)=1	
IZ=IY	
160 IZ=D(IZ)	
IF (IZ.GT.N) GO TO 160	LUS0 8000
K = K+1	LUS0 8100

IH1(K)=IY	
IH2(K)=IZ	
IF (SWP) ND(IZ)=ND(IZ-1)	
GO TO 140	LUS0 8500
170 IY = IX	LUS0 8600
C COLLECT THE RIGHT CONNECTED ARCS	LUS0 8700
C WITH THEIR LEFT INDEX VALUES	LUS0 8800
180 IY=C(IY)	
IF (IY.EQ.IX) GO TO 195	LUS0 9000
IF (T(IY).EQ.1) GO TO 180	
IZ = IY	LUS0 9200
190 IZ=R(IZ)	
IF (IZ.GT.N) GO TO 190	LUS0 9400
K = K+1	LUS0 9500
IH1(K)=IY	
IH2(K)=IZ	
IF (SWP) ND(IZ)=ND(IZ-1)	
L(IY)=1	
T(IY)=1	
GO TO 190	LUS1 0100
195 IF (K.EQ.I) GO TO 300	LUS1 0200
K1 = I+1	LUS1 0300
C LOOP ON THE COLLECTED ARCS	LUS1 0400
DO 250 J1=K1,K	LUS1 0500
IY=IH1(J1)	
IZ=IH2(J1)	
Y = B(IY)	LUS1 0800
C DIVIDE THE ELEMENT BY THE PIVOT AND	LUS1 0900
C MODIFY ITS CORRESPONDING DIAGONAL	LUS1 1000
B(IY) = B(IY)/XMAX	LUS1 1100
B(IZ) = B(IZ) - B(IY)*Y	LUS1 1200
IF (ABS(B(IY)).GT.CT2)	LUS1 1300
1 CT2 = ABS(B(IY))	LUS1 1400
IF (ABS(B(IZ)).GT.CT2)	LUS1 1500
1 CT2 = ABS(B(IZ))	LUS1 1600
IF (J1.EQ.K) GO TO 250	LUS1 1700
K2 = J1+1	LUS1 1800
C INSIDE LOOP FOR THE REST OF THE COLLECTED ARCS	LUS1 1900
C TO MODIFY THE INTERSECTING ARCS	LUS1 2000
DO 240 J2=K2,K	LUS1 2100
IY1=IH1(J2)	
IZ1=IH2(J2)	
C FIND THE ARC W BETWEEN IZ-IZ1 DIRECTED FROM	LUS1 2400
C MIN(IZ,IZ1) TO MAX(IZ,IZ1) IF EXISTS	LUS1 2500
I1 = MIN0(IZ,IZ1)	LUS1 2600
I2 = MAX0(IZ,IZ1)	LUS1 2700
L1=R(I1)	
L2=C(I2)	
200 IF (L1.EQ.I1.OR.L2.EQ.I2)	LUS1 3000
< GO TO 220	LUS1 3100
IF (L1.EQ.L2) GO TO 230	LUS1 3200
IF (L1.GT.L2) GO TO 210	LUS1 3300
L2=C(L2)	
GO TO 200	LUS1 3500
210 L1=R(L1)	

GO TO 230	LUS13700
C IT DOES NOT EXIST, THUS CREATE ONE	
220 IF (M.E1.MX) GO TO 950	LUS13900
M = M+1	LUS14000
IF (SWP) ND(I1)=ND(I1+1)	
IF (SWP) ND(I2)=ND(I2+1)	
L1 = M	LUS14300
IF (L1.GE.16000) WRITE (6,261)L1	
261 FORMAT(1X,3HAAA,I15)	LUS14400
B(L1) = 0.	
R(L1)=R(I1)	
C(L1)=C(I2)	
R(I1)=L1	
C(I2)=L1	
L(L1)=0	
T(L1)=0	
C MODIFY THE VALUE OF THE INTERSECTING ARC	LUS15100
230 B(L1) = B(L1)-B(IY)*B(IY1)	LUS15200
IF (ABS(B(L1)).GT.CT2)	LUS15300
1 CT2 = ABS(B(L1))	LUS15400
240 CONTINUE	LUS15500
250 CONTINUE	LUS15600
300 CONTINUE	LUS15700
RETJRN	LUS15800
C	LUS15900
C **** ERRORS ****	LUS16000
C NUMERICALLY SINGULAR	LUS16100
900 WRITE (5,910) I	LUS16200
910 FORMAT (24H0 NUMERICALLY SINGULAR AT, I5)	LUS16300
STOP	LUS16400
C INSUFFICIENT STORAGE	LUS16500
950 WRITE (5,960) I	LUS16600
960 FORMAT (24H0 INSUFFICIENT STORAGE AT, I5)	LUS16700
STOP	LUS16800
END	LUS16900

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SUBROUTINE SOLVE (W)
*****
*
*   THE SOLVE SUBROUTINE SOLVES THE THE SYMMETRIC LINEAR SYSTEM
*   FOR THE GIVEN RIGHT HAND SIDE W. THE SOLUTION IS RETURNED
*   THROUGH W. THE COEFFICIENT MATRIX MUST HAVE BEEN DECOMPOSED PRIOR
*   TO CALLING THIS SUBROUTINE. THE CORRESPONDING SEQUENCE OF PIVOTS
*   IS ASSUMED TO BE IN THE IP ARRAY.
*
*****
C   LOOP TO SOLVE LOWER TRIANGULAR SYSTEM
C
C   STORAGE ASSIGNMENT FOR SYMMETRIC DECOMPOSITION
C   MX - THE MAXIMUM ALLOWED NUMBER OF NON-ZERO COEFFICIENTS,
C   NX - THE MAXIMUM ALLOWED SIZE OF THE MATRIX.
COMMON /DIM/ MX, NX
C   ARRAYS OF SIZE M -
C   R - INTEGER ARRAY USED FOR ROW LINKAGE
C   C - INTEGER ARRAY USED FOR COLUMN LINKAGE
C   L - INTEGER ARRAY USED FOR TAGGING ( 0 OR 1 )
C   T - INTEGER ARRAY USED FOR TAGGING ( 0 OR 1 )
C   B - FL. PT. ARRAY CONTAINING THE VALUES OF THE COEFFICIENTS
C   THE ARRAYS R,C,L AND T CONTAIN PACKED INTEGERS.
COMMON /ARRAYM/ R(5000),C(5000),L(5000),T(5000),B(2000)
INTEGER R,C,T
C   ARRAYS OF SIZE N -
C   IP - INTEGER ARRAY CONTAINS THE SEQUENCE OF PIVOTS
C   ND - INTEGER ARRAY CONTAINS THE NUMBER OF ELEMENTS
C   IN A ROW OF THE UNDECOMPOSED PART OF THE MATRIX
C   IH1, IH2 - ARE TEMPORARY INTEGER ARRAYS, ONE OF THEM
C   MAY BE EQUIVALENCED TO IP
COMMON /ARRAYN/ IP(500),ND(500),IH1(500),IH2(500)
C   INDIVIDUAL DATA -
C   M - NUMBER OF NONZERO ELEMENTS
C   N - SIZE OF THE MATRIX
C   UP - PIVOT SELECTION PARAMETER
C   CT1 - MAXIMUM ELEMENT IN THE ORIGINAL MATRIX
C   CT2 - MAXIMUM ELEMENT ENCOUNTERED DURING DECOMPOSITION
COMMON /DATA/ M,N,CT1,CT2
C
C   DIMENSION W(1)
C
C   DO 100 I=2,N
C     IX=IP(I)
C     IY=IX
C20  IY=R(IY)
C     IF (IY.EQ.IX) GO TO 40
C     IF (L(IY).EQ.0) GO TO 20
C     IZ = IY
C30  IZ=C(IZ)
C     IF (IZ.GT.N) GO TO 30
C     W(IX) = W(IX)-W(IZ)*B(IY)
C     GO TO 20
C40  IY = IX
C50  IY=C(IY)

```

IF (IY.EQ.IX) GO TO 100	SS002800
IF (L(IY).EQ.1) GO TO 50	
IZ = IY	SS003000
60 IZ=R(IZ)	
IF (IZ.GT.N) GO TO 50	SS003200
W(IX) = W(IX)-W(IZ)*B(IY)	SS003300
GO TO 50	SS003400
100 CONTINUE	SS003500
C LOOP TO SOLVE DIAGONAL SYSTEM	SS003600
DO 110 I=1,N	SS003700
110 W(I) = A(I)/B(I)	SS003800
C LOOP TO SOLVE TRANSPOSED UPPER TRIANGULAR SYSTEM	SS003900
DO 200 I=2,N	SS004000
K = N+1-I	SS004100
IX=IP(K)	
IY = IX	SS004300
120 IY=R(IY)	
IF (IY.EQ.IX) GO TO 140	SS004500
IF (L(IY).EQ.1) GO TO 120	
IZ = IY	SS004700
130 IZ=C(IZ)	
IF (IZ.GT.N) GO TO 130	SS004900
W(IX) = W(IX)-W(IZ)*B(IY)	SS005000
GO TO 120	SS005100
140 IY = IX	SS005200
150 IY=C(IY)	
IF (IY.EQ.IX) GO TO 200	SS005400
IF (L(IY).EQ.0) GO TO 150	
IZ = IY	SS005600
160 IZ=R(IZ)	
IF (IZ.GT.N) GO TO 160	SS005800
W(IX) = W(IX)-W(IZ)*B(IY)	SS005900
GO TO 150	SS006000
200 CONTINUE	SS006100
RETJRN	SS006200
END	SS006300

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